

# Math 2177 recitation: Matrix and vectors

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## 1 Different forms of equations and matrix operations

Given a system of linear equations, for example:

$$2x_1 + 3x_2 - x_3 = 4$$

$$5x_1 - 3x_2 - 4x_3 = 1$$

$$2x_1 + x_2 + 7x_3 = 10$$

There's three other different ways of presenting this system:

By augmented matrix: 
$$\left[ \begin{array}{ccc|c} 2 & 3 & -1 & 4 \\ 5 & -3 & -4 & 1 \\ 2 & 1 & 7 & 10 \end{array} \right]$$

By vector equation: 
$$x_1 \begin{bmatrix} 2 \\ 5 \\ 2 \end{bmatrix} + x_2 \begin{bmatrix} 3 \\ -3 \\ 1 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ -4 \\ 7 \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \\ 10 \end{bmatrix}$$

By matrix equation: 
$$\begin{bmatrix} 2 & 3 & -1 \\ 5 & -3 & -4 \\ 2 & 1 & 7 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \\ 10 \end{bmatrix}$$
, here on left hand side we

are taking product of two matrices.

Recall for matrices  $\mathbf{A}$  and  $\mathbf{B}$ . The  $(i, j)$  entry of their product  $\mathbf{AB}$  (if defined) is the dot product (  $i$ th row of  $\mathbf{A}$  )  $\cdot$  (  $j$ th column of  $\mathbf{B}$  )

**Example :**

$$\begin{bmatrix} 0 & 1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 4 & 5 \\ 6 & 7 \end{bmatrix} = \begin{bmatrix} 0*4 + 1*6 & 0*5 + 1*7 \\ 2*4 + 3*6 & 2*5 + 3*7 \end{bmatrix} = \begin{bmatrix} 6 & 7 \\ 26 & 31 \end{bmatrix}$$

**Exercise1 :** Compute the following matrix operations. Write "undefined" for expressions that are undefined.

(1)  $3 \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

(2)  $[10 \ 20 \ 30] - [1 \ 2 \ 3]$

$$(3) \quad \begin{bmatrix} 3 & 1 \\ -3 & -4 \end{bmatrix} \begin{bmatrix} 1 & -3 \\ -4 & -1 \end{bmatrix}$$

$$(4) \quad \begin{bmatrix} 1 & -3 \\ -4 & -1 \end{bmatrix} \begin{bmatrix} 3 & 1 \\ -3 & -4 \end{bmatrix}$$

$$(5) \quad \begin{bmatrix} 3 & 2 \\ 2 & 1 \\ 3 & 4 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 2 & -6 \end{bmatrix} \begin{bmatrix} -2 & 6 \\ 0 & 0 \end{bmatrix}$$

$$(6) \quad \begin{bmatrix} 4 & -5 & 4 & 0 \\ 6 & 3 & 0 & -3 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ -6 & -1 \end{bmatrix}$$

## 2 Connection between homogeneous and non homogeneous equations

Consider matrix equation  $\mathbf{A}\bar{x} = \bar{b}$ , where  $\mathbf{A}$  is a matrix,  $\bar{x}, \bar{b}$  are vectors. If we already know a solution  $\bar{p}$ , i.e.  $\mathbf{A}\bar{p} = \bar{b}$ , then any solution of  $\mathbf{A}\bar{x} = \bar{b}$  can be write as  $\bar{x} = \bar{p} + \bar{h}$ , where  $\bar{h}$  is solution of corresponding homogeneous equation  $\mathbf{A}\bar{x} = 0$ . This is because  $\mathbf{A}(\bar{x} - \bar{p}) = \mathbf{A}\bar{x} - \mathbf{A}\bar{p} = \bar{b} - \bar{b} = 0$ .

**Exercise2** : Let  $\mathbf{A} = \begin{bmatrix} 1 & 2 & 0 & 4 \\ 0 & 0 & 1 & 6 \end{bmatrix}$  and let  $\mathbf{A} \cdot \begin{bmatrix} 2 \\ 0 \\ 1 \\ 0 \end{bmatrix} = \bar{b}$ . Find the general solution

to  $\mathbf{A}\bar{x} = \bar{b}$ .

### 3 Linear combination and linearly dependence

Say vector  $\bar{u}$  is a linear combination of vectors  $\bar{v}_1, \bar{v}_2, \dots, \bar{v}_k$  if the equation

$$x_1\bar{v}_1 + x_2\bar{v}_2 + \dots + x_k\bar{v}_k = \bar{u}$$

has solutions.

Say vectors  $\bar{v}_1, \bar{v}_2, \dots, \bar{v}_k$  are linearly dependent if the equation

$$x_1\bar{v}_1 + x_2\bar{v}_2 + \dots + x_k\bar{v}_k = 0$$

has **nonzero** solutions. Otherwise  $\bar{v}_1, \bar{v}_2, \dots, \bar{v}_k$  are called linearly independent

**Exercise3** : Determine which of the following lists of vectors are linearly independent:

$$(1) \bar{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 0 \\ -1 \\ 5 \end{bmatrix}, \bar{v}_2 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \bar{v}_3 = \begin{bmatrix} 16 \\ 6 \\ 2 \\ -7 \\ 0 \end{bmatrix},$$

$$(2) \bar{v}_1 = \begin{bmatrix} 5 \\ 7 \end{bmatrix}$$

$$(3) \bar{v}_1 = \begin{bmatrix} 3 \\ 1 \\ 4 \end{bmatrix}, \bar{v}_2 = \begin{bmatrix} -2 \\ 2 \\ 5 \end{bmatrix}, \bar{v}_3 = \begin{bmatrix} 3 \\ 0 \\ 4 \end{bmatrix}, \bar{v}_4 = \begin{bmatrix} 2 \\ -1 \\ -2 \end{bmatrix}$$

$$(4) \bar{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \bar{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \bar{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \bar{v}_4 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$(5) \bar{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \bar{v}_2 = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}, \bar{v}_3 = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$$