Ralph's random probability and variance

This is a continuation of Ralph's uncertain variance. Everything is the same except Ralph views the proposition probability p (that the state is favorable) as a random variable (in other words, Ralph is uncertain about the probability assignment for the proposition). Accordingly, Ralph believes $E [\log p] = E [\log 1 - p] = -1.96191$ (geometric mean $\exp(-1.96191) = 0.14059$) or, in other words, p has a beta distribution with concentration parameters a = b = 0.3.

Ralph knows Bayesian (sum and product rules) updating of the proposition probability based on conditionally normally distributed evidence (with a given variance) is

$$\begin{aligned} &f\left(p\mid y=24;\sigma\right)\\ &= \quad \frac{f\left(p,y=24;\sigma\right)}{f\left(y=24;\sigma\right)}\\ &= \quad \frac{\left[pf\left(y=24\mid s=f\right)+\left(1-p\right)f\left(y=24\mid s=u\right)\right]p^{a-1}\left(1-p\right)^{b-1}}{\int_{0}^{1}\left[pf\left(y=24\mid s=f\right)+\left(1-p\right)f\left(y=24\mid s=u\right)\right]p^{a-1}\left(1-p\right)^{b-1}dp} \end{aligned}$$

where $f(y \mid s)$ is a normal density function and the denominator is

$$f(y = 24; \sigma) = \beta (1 + a, b) f(y = 24 | s = f) + \beta (a, 1 + b) f(y = 24 | s = u)$$

and $\beta (a, b) = \frac{\Gamma(a)\Gamma(b)}{\Gamma(a+b)}$. Also,
$$E[p | y = 24; \sigma]$$
$$= \frac{\frac{1+a}{1+a+b}\beta (1 + a, b) f(y = 24 | s = f) + \frac{a}{1+a+b}\beta (a, 1+b) f(y = 24 | s = u)}{f(y = 24; \sigma)}$$

When the variance or standard deviation σ is also uncertain with kernel $\frac{1}{\sigma}$ Bayesian updating of the proposition probability is

$$\begin{aligned} &f\left(p\mid y=24; 1<\sigma<3\right)\\ &=\quad \frac{f\left(p, y=24; 1<\sigma<3\right)}{f\left(y=24; 1<\sigma<3\right)}\\ &=\quad \frac{\int_{1}^{3}\frac{1}{\sigma}\left[pf\left(y=24\mid s=f\right)+(1-p)\,f\left(y=24\mid s=u\right)\right]p^{a-1}\left(1-p\right)^{b-1}d\sigma}{\int_{0}^{1}\int_{1}^{3}\frac{1}{\sigma}\left[pf\left(y=24\mid s=f\right)+(1-p)\,f\left(y=24\mid s=u\right)\right]p^{a-1}\left(1-p\right)^{b-1}d\sigma dp}\end{aligned}$$

where the numerator is

$$\begin{split} f\left(p, y = 24; 1 < \sigma < 3\right) &= p^{a} \left(1 - p\right)^{b-1} \frac{\left[F\left(\frac{24 - \mu_{f}}{3}\right) - F\left(\frac{24 - \mu_{f}}{1}\right)\right]}{\mu_{f} - 24} \\ &+ p^{a-1} \left(1 - p\right)^{b} \frac{\left[F\left(\frac{24 - \mu_{u}}{3}\right) - F\left(\frac{24 - \mu_{u}}{1}\right)\right]}{\mu_{u} - 24} \end{split}$$

 $F\left(\right)$ is the cumulative standard normal distribution function, μ_{j} is the mean of y conditional on state j and the denominator is

$$\begin{split} f\left(y=24; 1<\sigma<3\right) &= \beta\left(1+a,b\right) \frac{\left[F\left(\frac{24-\mu_f}{3}\right) - F\left(\frac{24-\mu_f}{1}\right)\right]}{\mu_f - 24} \\ &+\beta\left(a, 1=b\right) \frac{\left[F\left(\frac{24-\mu_u}{3}\right) - F\left(\frac{24-\mu_u}{1}\right)\right]}{\mu_u - 24} \end{split}$$

And,

$$E\left[p \mid y = 24; 1 < \sigma < 3\right] \\ = \begin{cases} \frac{1+a}{1+a+b}\beta\left(1+a,b\right)\frac{\left[F\left(\frac{24-\mu_f}{3}\right) - F\left(\frac{24-\mu_f}{1}\right)\right]}{\mu_f - 24} \\ +\frac{a}{1+a+b}\beta\left(a,1=b\right)\frac{\left[F\left(\frac{24-\mu_u}{3}\right) - F\left(\frac{24-\mu_u}{1}\right)\right]}{\mu_u - 24} \end{cases}\right\} / f\left(y = 24; 1 < \sigma < 3\right)$$

Suggested:

1. Verify via maximum entropy probability assignment the kernel for p is $p^{-0.7}\left(1-p\right)^{-0.7}.$

2. Derive the density function for proposition probability given the evidence $f(p \mid y = 24; \sigma)$ and expected value $E[p \mid y = 24; \sigma]$ if σ is assigned 1 or if σ is assigned 3.

3. Derive the density function for proposition probability given the evidence $f(p \mid y = 24; 1 < \sigma < 3)$ and expected value $E[p \mid y = 24; 1 < \sigma < 3]$ if σ is assigned density $\frac{1}{\sigma}$ with support between 1 and 3.

4. How do these results compare with those in Ralph's uncertain variance?