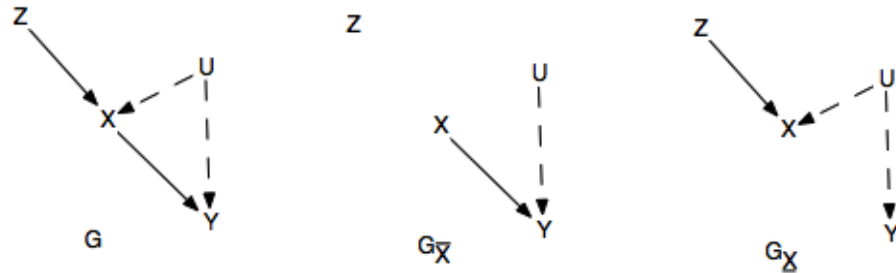


Ralph's partially-identified DAG

Ralph wishes to identify causal effects associated with the DAG below where Z is treatment assigned, X is treatment received, Y is outcome or response, and U is latent (unobserved) factors.



DAG G and its subgraphs

Suppose Y, X , and Z are binary and Ralph focuses on the aggregate or average causal effect¹

$$ACE(X \rightarrow Y) = \Pr(y_1 | do(x_1)) - \Pr(y_1 | do(x_0))$$

Suggested:

1. Suppose $W = U$ where W is observable. Can Ralph employ a back-door adjustment (see Ralph's back-door adjustment) to point-identify causal effects of X on Y ? In this W observable setting, is it necessary for Ralph to condition on Z to identify causal effects of X on Y ?

2. With U unobservable, can Ralph point-identify causal effects? Hint: can the back-door adjustment be implemented?

As a result of the challenges associated with latent factors U , Ralph decides an alternative frame is in order. Let R_x be a variable describing compliance behavior where $r_x = 0, 1, 2, 3$ denotes, respectively, a never-taker, complier, defier, and always-taker. Then,

$$x = \begin{cases} x_0 & \text{if } r_x = 0, \\ x_0 & \text{if } r_x = 1 \text{ and } Z = z_0, \\ x_1 & \text{if } r_x = 1 \text{ and } Z = z_1, \\ x_1 & \text{if } r_x = 2 \text{ and } Z = z_0, \\ x_0 & \text{if } r_x = 2 \text{ and } Z = z_1, \\ x_1 & \text{if } r_x = 3 \end{cases}$$

¹Since Y is binary $E[Y] = \Pr(y_1)$.

Likewise, let the variable R_y convey response to treatment where $r_y = 0, 1, 2, 3$ represents never-recover, helped, harmed, always-recover, respectively.

$$y = \begin{array}{ll} y_0 & \text{if } r_y = 0, \\ y_0 & \text{if } r_y = 1 \text{ and } X = x_0, \\ y_1 & \text{if } r_y = 1 \text{ and } X = x_1, \\ y_1 & \text{if } r_y = 2 \text{ and } X = x_0, \\ y_0 & \text{if } r_y = 2 \text{ and } X = x_1, \\ y_1 & \text{if } r_y = 3 \end{array}$$

3. Determine $\Pr(y_1 | do(x_1))$, $\Pr(y_1 | do(x_0))$, and $ACE(X \rightarrow Y)$ in terms of r_y .

Further, Ralph recognizes that causal effect identification demands that he work with distributions over observables. In this case, the conditional distributions, $\Pr(y, x | z_0)$ and $\Pr(y, x | z_1)$, are observable. For simplicity, Ralph denotes the conditional distributions $p_{ij.k}$ where $i, j, k = 0, 1$ for y_i, x_j, z_k .

Ralph knows Pearl describes natural bounds on the causal effects.

$$p_{11.1} \leq \Pr(y_1 | do(x_1)) \leq 1 - p_{01.1}$$

and

$$p_{10.0} \leq \Pr(y_1 | do(x_0)) \leq 1 - p_{00.0}$$

4. Write an expression for the natural bounds on $ACE(X \rightarrow Y)$ in terms of $p_{ij.k}$.

Suppose the *DGP* (data generating process) is

$$\begin{array}{ll} p_{00.0} = 0.919 & p_{00.1} = 0.315 \\ p_{01.0} = 0.000 & p_{01.1} = 0.139 \\ p_{10.0} = 0.081 & p_{10.1} = 0.073 \\ p_{11.0} = 0.000 & p_{11.1} = 0.473 \\ \Pr(z_1) = 0.500 & \Pr(z_0) = 0.500 \end{array}$$

5. What is the compliance rate, $\Pr(x_1 | z_1)$?

6. What is the encouragement or intent to treat effect, $\Pr(y_1 | z_1) - \Pr(y_1 | z_0)$?²

7. What is the mean (observation not action) difference $\Pr(y_1 | x_1) - \Pr(y_1 | x_0)$?

²Policy decisions are sometimes based on this effect due to partial compliance complications.

8. What are the natural bounds on $\Pr(y_1 | do(x_1))$, $\Pr(y_1 | do(x_0))$, and $ACE(X \rightarrow Y)$?

The natural bounds can be tightened via usage of a dual linear program. The lower bound on $\Pr(y_1 | do(x_1))$ is

$$\Pr(y_1 | do(x_1)) \geq \max \left\{ \begin{array}{c} p_{11.1}, \\ p_{11.0}, \\ -p_{00.0} - p_{01.0} + p_{00.1} + p_{11.1}, \\ -p_{01.0} - p_{10.0} + p_{10.1} + p_{11.1} \end{array} \right\}$$

The upper bound on $\Pr(y_1 | do(x_1))$ is

$$\Pr(y_1 | do(x_1)) \leq \min \left\{ \begin{array}{c} 1 - p_{01.1}, \\ 1 - p_{01.0}, \\ p_{00.0} + p_{11.0} + p_{10.1} + p_{11.1}, \\ p_{10.0} + p_{11.0} + p_{00.1} + p_{11.1}, \end{array} \right\}$$

The lower bound on $\Pr(y_1 | do(x_0))$ is

$$\Pr(y_1 | do(x_0)) \geq \max \left\{ \begin{array}{c} p_{10.1}, \\ p_{10.0}, \\ p_{10.0} + p_{11.0} - p_{00.1} - p_{11.1}, \\ p_{01.0} + p_{10.0} - p_{00.1} - p_{01.1} \end{array} \right\}$$

The upper bound on $\Pr(y_1 | do(x_0))$ is

$$\Pr(y_1 | do(x_0)) \leq \min \left\{ \begin{array}{c} 1 - p_{00.1}, \\ 1 - p_{00.0}, \\ p_{01.0} + p_{10.0} + p_{10.1} + p_{11.1}, \\ p_{10.0} + p_{11.0} + p_{01.1} + p_{10.1}, \end{array} \right\}$$

9. What are the linear programming bounds on $\Pr(y_1 | do(x_1))$, $\Pr(y_1 | do(x_0))$, and $ACE(X \rightarrow Y)$? Interpret the results in light of the degree of noncompliance.

10. Ralph is also interested in the effect of the existing program under its current incentive system and current participants which is treatment on treated. Average treatment on the treated is quantified as

$$\begin{aligned} ETT(X \rightarrow Y) &= \Pr(Y_{\hat{x}_1} = y_1 | x_1) - \Pr(Y_{\hat{x}_0} = y_1 | x_1) \\ &= \sum_u [\Pr(y_1 | x_1, u) - \Pr(y_1 | x_0, u)] \Pr(u | x_1) \end{aligned}$$

where $Y_{\hat{x}_j}$ refers to outcome when intervening with action x_j and conditioning on x_1 refers to the subpopulation observed in the treatment regime. Again,

this utilizes unobservable U so Ralph employs partial identification once again. Natural bounds on ETT are

$$\begin{aligned} & \frac{P(y_1) - P(x_1 | z_0) - P(y_1, x_0 | z_0)}{P(x_1)} \\ \leq & ETT(X \rightarrow Y) \leq \\ & \frac{P(y_1) - P(y_1, x_0 | z_0)}{P(x_1)} \end{aligned}$$

Natural bounds on the untreated (say, $ETUT$) complement natural bounds on the treated to give the natural bounds on ACE as

$$ACE(X \rightarrow Y) = \Pr(x_1) ETT(X \rightarrow Y) + \Pr(x_0) ETUT(X \rightarrow Y)$$

where

$$\begin{aligned} & \frac{-P(y_1) + P(y_1, x_1 | z_1)}{P(x_0)} \\ \leq & ETUT(X \rightarrow Y) \leq \\ & \frac{-P(y_1) + P(x_0 | z_1) + P(y_1, x_1 | z_1)}{P(x_0)} \end{aligned}$$

Determine the natural bounds for ETT , and $ETUT$ and verify their complementarity with ACE .

Alternatively, suppose the DGP is

$$\begin{array}{ll} p_{00.0} = 0.55 & p_{00.1} = 0.45 \\ p_{01.0} = 0.45 & p_{01.1} = 0. \\ p_{10.0} = 0. & p_{10.1} = 0. \\ p_{11.0} = 0. & p_{11.1} = 0.55 \\ \Pr(z_1) = 0.50 & \Pr(z_0) = 0.50 \end{array}$$

11. Repeat 5 through 10 for this DGP .