

main.asm

```

1 ;-----
2 ; MSP430 Assembler Code Template for use with TI Code Composer Studio
3 ;
4 ;
5 ;-----
6     .cdecls C,LIST,"msp430.h"      ; Include device header file
7
8 ;-----
9     .def      RESET                ; Export program entry-point to
10                                ; make it known to linker.
11 ;-----
12     .data                          ; Assemble into program memory.
13     .retain                        ; Override ELF conditional linking
14                                ; and retain current section.
15     .retainrefs                    ; And retain any sections that have
16                                ; that have references to current
17                                ; section
18
19 count:    .space 2                ; count of timer interrupts since the program
    started
20 count0:   .space 2                ; Value of count variable at the time counter is
    started
21 count1:   .space 2                ; Value of count variable at the time counter is
    stopped
22 result:   .space 2                ; result = count1 - count0
23
24 cstatus:  .space 1                ; Zeroth bit of cstatus stores your counter's
    status bit. 0 means counter stopped, 1 means counter running
25
26 ;-----
27     .text                          ; Assemble into program memory.
28     .retain                        ; Override ELF conditional linking
29                                ; and retain current section.
30     .retainrefs                    ; And retain any sections that have
31                                ; references to current section.
32
33 ;-----
34 RESET    mov.w    #__STACK_END,SP    ; Initialize stackpointer
35 StopWDT  mov.w    #WDTPW|WDTHOLD,&WDTCTL ; Stop watchdog timer
36
37
38 ;-----
39 ; Main loop here
40
41     ; P1.0 is connected to the red LED
42     bic.b    #BIT0, &P1OUT    ; start with LED off
43     bis.b    #BIT0, &P1DIR    ; Set P1.0 as output pin
44
45     ; Configure Push Button S1 (Port 1, Pin 1)
46     bis.b    #BIT1, &P1REN    ; Enable Resistor
47     bis.b    #BIT1, &P1OUT    ; Pull-up resistor, since S1 is active low
48     bis.b    #BIT1, &P1IE    ; Enable P1.1 interrupts
49     bis.b    #BIT1, &P1IES    ; Enable Loweing Edge
50     bic.b    #BIT1, &P1IFG
51
52     ; Configer timer B0, connected to ACLK, to raise interrupts
53     bis.w    #TBCLR, &TB0CTL

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54     bis.w #TBSEL__ACLK, &TB0CTL
55     bis.w #MC__CONTINUOUS, &TB0CTL
56     bis.w #TBIE, &TB0CTL
57     bic.w #TBIFG, &TB0CTL
58
59 UnlockGPIO: bic.w  #LOCKLPM5,&PM5CTL0      ; Disable the GPIO power-on default
60
61     nop                                ; no operation
62     bis.w  #GIE|LPM3,  SR                ; sleep in LPM3 mode and wait for interrupts
63     nop                                ; no operation
64
65 ;-----
66 ;                                ISRs
67 ;-----
68
69 PORT1_ISR:
70
71     xor.b  #BIT0, &P1OUT      ; Toggle P1.0
72     xor.b  #BIT0, &cstatus    ; Toggle counter status flag
73
74     bit.b  #BIT0,  &cstatus    ; if cstatus' 0th bit is 1 (counter running)
75     jnc IF1_EXIT
76         mov.w  &count,  &count0
77 IF1_EXIT:
78
79     bit.b  #BIT0,  &cstatus    ; if cstatus' 0th bit is 0 (counter stopping)
80     jc  IF2_EXIT
81         mov.w  &count,  &count1
82         mov.w  &count1, &result
83         sub.w  &count0, &result ;result = count1 - count0
84
85 IF2_EXIT:
86
87     bic.b  #BIT1, &P1IFG      ; Multisourced Interrupt so clear interrupt flag
88     reti
89
90 ;-----
91
92 Timer_Overflow:
93     inc.w  &count              ; increase count by 1
94     bic.w  #TBIFG, &TB0CTL    ; Multisourced Interrupt so clear interrupt flag
95     reti
96
97 ;-----
98 ; Stack Pointer definition
99 ;-----
100     .global __STACK_END
101     .sect  .stack
102
103 ;-----
104 ; Interrupt Vectors
105 ;-----
106     .sect  ".reset"           ; MSP430 RESET Vector
107     .short RESET
108
109     .sect  ".int37"           ; PORT1 Vector
110     .short PORT1_ISR

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111
112     .sect    ".int50"                ; TIMER Vector
113     .short   Timer_Overflow
114
115
```