# The Little AEV that Could

9529 Team C: Nick Braun, Jeffrey Gaydos, and Samira Wehmann

# **Design Process**

Four designs were originally created:

- Tiana's Design 1.
- 2. The Airplane
- 3. The Mystic Macaw
- 4. Coaxial Contra-Rotating Propellers

Design's 3 and 4 were combined to create "The Bullet":



#### Figure 1: "The Bullet" Original AEV Design Issues: Advantages:

- Heavv
  - Unbalanced
- Hard to maintain
- Insecure motors



Figure 2: Second AEV Design

Issues: •

Wires

#### Advantages: •

- Secure Motors insecure Balanced Easy to Maintain
- Not • aerodynamic 

  Lightweight

# Aerodynamic Aesthetics

- Holds down
- wires



## Material Cost: \$238,800

of Final Design

The AEV preformed less than expected due to time constraints and inconsistencies in the AEV's code. It used considerably more time and energy than expected and the code could have been improved to make the AEV more consistent.

Average Run Time: 79.75 seconds

Average Run Energy: 469.65 joules

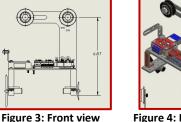
### ACKNOWLEDGEMENTS

The team would like to thank Microsoft for their PowerPoint program that aided in creating the [11 Ohio State Fundamentals of Engineering Program. "AEV Student Kit Checklist" (Course photoshopped picture above. The team also thanks all the UTAs especially Quent and Jordan Documentation]. Available: carmen.osu.edu for ENGR1182. [Accessed Jan. 29, 2019 - Present] and the Instructors for answering questions and directing us in creating the AEV.

# **Final Design**

The final design includes the following features:

- Coaxial contra-rotating propellers •
- Standoffs for the propellers to hang below the AEV
- . Battery holder located on top of base
- Cushioned magnet connection
- Arm centered for balance
- Wires secured with Zip-ties



**Figure 4: Isometric** view of Final Design

# **Final Materials Cost**

Component	Amount	Unit Price	Total Price	<b>Budget Unit Cost</b>
Arduino	1	\$100.00	\$100.00	\$100,000.00
Electric Motors	2	\$9.99	\$19.98	\$9,990.00
Count Sensor	2	\$2.00	\$4.00	\$2,000.00
Count Sensor Connector	2	\$2.00	\$4.00	\$2,000.00
1"x3" Rectangle	2	\$1.00	\$2.00	\$1,000.00
2"x6" Rectangle	1	\$2.00	\$2.00	\$2,000.00
Battery Risers	4	\$2.00	\$8.00	\$2,000.00
Motor Clamps	2	\$0.59	\$1.18	\$590.00
L-Shape Arm	1	\$3.00	\$3.00	\$3,000.00
Wheels	2	\$7.50	\$15.00	\$7,500.00
Large Wheel Nut	2	\$1.00	\$2.00	\$1,000.00
Large Wheel Bolt	2	\$1.00	\$2.00	\$1,000.00
Battery Supports	1	\$1.00	\$1.00	\$1,000.00
Battery Risers	2	\$1.00	\$2.00	\$1,000.00
Propellers	2	\$0.45	\$0.90	\$450.00
Angle Brackets	4	\$0.84	\$3.36	\$840.00
Bulk Screws and Nuts	1	\$2.88	\$2.88	\$2,880.00
Custom Shell	1	\$65.50	\$65.50	\$65,500.00
		Total	\$238.80	\$238,800.00

Figure 5: Final Design on Track

Photoshopped with Team

Magnet connector

**Propellers** secured

with extra pieces

cushion load

connection

moves with friction to

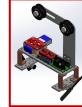
# Advanced R&D

Advanced R&D 1: Battery

٠ Small changes in voltage do not affect speed

Advanced R&D 2: Propellers

٠ Contra-rotating propeller configuration chosen (see Figure 6, below and left)



- Advanced R&D 3: Wheel Position
- Wheel position is uncorrelated with position the AEV travels Revealed

Figure 6: Chosen Configuration

inconsistency of **Reflectance Sensors** 

# Performance Test 1 & 2

Results: ٠

- propeller broke
- shell was too heavy
- the AEV was not consistent
- AEV was unbalanced
- . added magnet connector

#### Takeaways:

- remove the shell •
- secure the wires •
- code revolved around •
- distance and braking then going minimum speed to pick up load