

```
//Positions are for upstairs track
//First quarter
reverse(4);
motorSpeed(4,22);
goToRelativePosition(230);
brake(4);
goFor(7); //stop at gate for 7 seconds

//2nd quarter
motorSpeed(4,22);
goToRelativePosition(318);
celerate(4,20,0,2); //or just do brake(4)
```