```
reverse(4);
```

```
// Run all motors at a constant speed of 30% power for 4 seconds
motorSpeed(4,30);
goFor(4);
```

```
//stop all motors for 10 seconds
motorSpeed(4,0);
goFor(10);
```

```
//Save the program as ExternalSensorsOutside
```

```
//reflectanceSensorTest();
```