

```
// Run all motors at a constant speed of 25% power for 2 seconds
```

```
motorSpeed(4,25);
```

```
goFor(2);
```

```
//Run all motors at a constant speed of 20% and using the goToAbsolutePosition function travel a total distance of 16 feet (from the starting point
```

```
motorSpeed(4,20);
```

```
goToAbsolutePosition(394);
```

```
//Reverse motors
```

```
reverse(4);
```

```
// Run all motors at a constant speed of 30% power for 1.5 seconds
```

```
motorSpeed(4,30);
```

```
goFor(1.5);
```

```
//Brake all motors
```

```
brake(4);
```

```
//Save the program as ExternalSensorsOutside
```