# AEV Critical Design Report

Team F

### Team F

#### Abhishekh (Coding)

 Responsible for programming the AEV to fulfill mission requirements

#### Vincent (Design + Coding)

 Assists with coding if there are issues and responsible for consolidating design choices

#### **Iskandar (Quantitative Analysis)**

Assists with all aspects of the mission and responsible for calculations

#### <u>Jacob (Design and Documentation)</u>

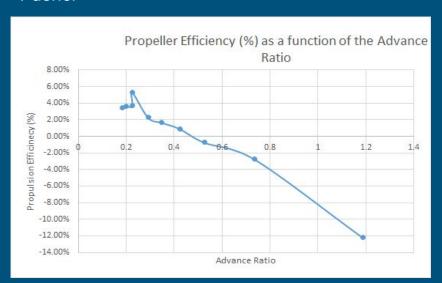
 Assists with designing the AEV and keeps documentation during meetings and coordinates team

### Overview of Presentation

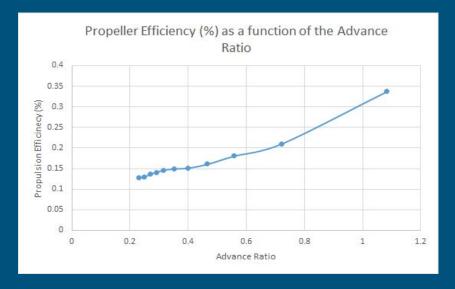
- Design Process
  - Pusher vs. Puller
  - o AEV
- Final Code
- Energy Performance
- Final Run



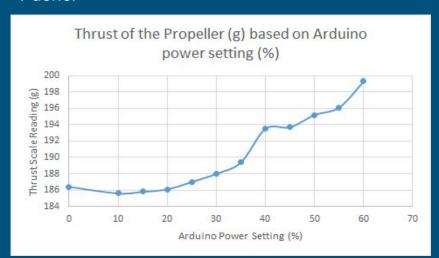
#### Pusher



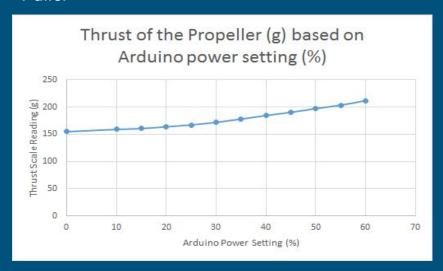
#### Puller



#### Pusher



#### Puller



### Considerations:

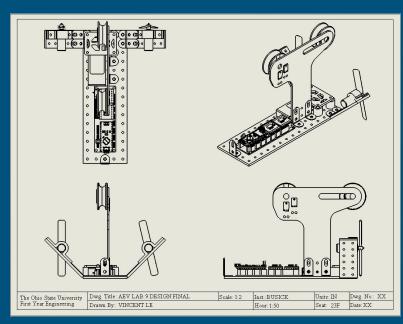
- Center-of-Mass/Turns
- Stability
  - Weight of AEV
- Track/Rail

### Model A:

- 90 degree wings to body
- Wings are tall to reduce inertia

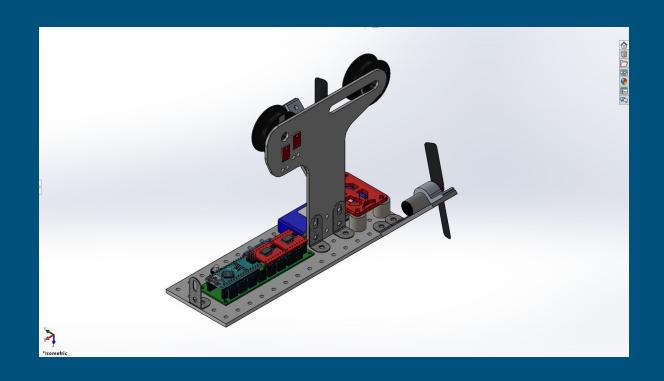
### Model B:

- 45 degree wings to body
- Motors moved inboard to compensate



Model B

# Final Design



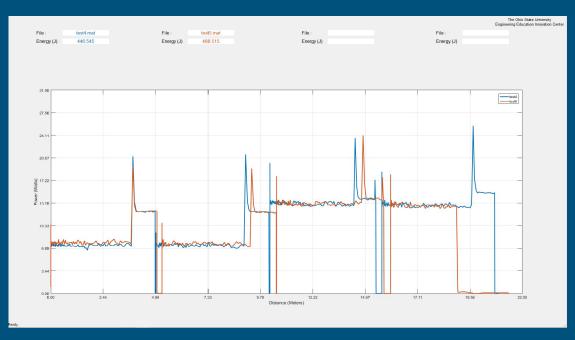
### Final Code

- Consistency vs. Energy Efficiency
  - Breaking Mechanism/ Reverse Thrust
  - Utilize the load's weight
    - Drift

### Performance

Energy

Comparison of energy usage(back thrust and coast)



### Performance

### Actual run



### Final Run

- Run 1:
  - Nothing went as planned.
  - o Reason: Sensor fell out

- Run 2:
  - MISSION COMPLETE!

