

```
reverse(4);
motorSpeed(4,25);
goToAbsolutePosition(309);
reverse(4);
motorSpeed(4,28);
goFor(2);
motorSpeed(4,0);
goFor(7.5);

reverse(4);
motorSpeed(4,25);
goToAbsolutePosition(595);
brake(4);
goFor(10);

reverse(4);
motorSpeed(4,30);
goToRelativePosition(-326);
reverse(4);
motorSpeed(4,35);
goFor(2);
brake(4);
goFor(7.5);

reverse(4);
motorSpeed(4,35);
goToRelativePosition(-245);
brake(4);
```