

```
motorSpeed(4,25);
goToAbsolutePosition(300);
reverse(4);
motorSpeed(4,30);
goFor(2);
motorSpeed(4,0);
goFor(8);
reverse(4);
motorSpeed(4,25);
goToAbsolutePosition(712);
reverse(4);
motorSpeed(4,30);
goFor(1.5);
brake(4);
goFor(2);
motorSpeed(4,35);
goToRelativePosition(-300);
```