Celebrate (4,0,25,2);	Accelerate all motors to 25% in 2 seconds
motorSpeed(4,25);	Set all motors' speed at 25%
goFor(2);	Run motors for 2 seconds
motorSpeed(4,20);	All motors power to 20%
goToAbsolutePosition(400);	Run until position 400 marks reached
reverse(4);	Reverse all motors
motorSpeed(4,30)	Run all motors at 30%
goFor(1.5);	Run motors for 1.5 seconds