

### Inside track code:

```
motorSpeed(4,25);      //Run all motors at a constant speed (25% power) for 2 second.  
goFor(2);
```

```
motorSpeed(4,20);      //Run all motors at a constant speed of 20% power  
goToAbsolutePosition(332); //Travel a distance of 13.5 feet
```

```
reverse(4);            //Reverse all motors.
```

```
motorSpeed(4,30);      //Run all motors at a constant speed (30% power) for 1 second.  
goFor(1.5);
```

```
brake(4);              //Brake all motors.  
                        //Save program as External Sensors Outside.
```