celerate(4,0,25,3); // Accelerate all motors from start to 25% in 3 seconds. motorSpeed(4,25); //Run all motors at a constant speed (25% power) for 1 second. goFor(1); motorSpeed(4,20); //Run all motors at 20% power for 2 seconds. goFor(2); reverse(4); //Reverse all motors. motorSpeed(4,25); //Run all motors at a constant speed (25% power) for 2 second. goFor(2); brake(4); //Brake all motors. //Save the program as CSS1