

# ICP: Solution algorithms



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# What

# Barrier

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# Barrier



Only inequality  
constraints!

We use a generic **inequality-constrained** nonlinear optimization problem of the form:

# Barrier

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f(x) \\ \text{s.t.} & g_1(x) \leq 0 \\ & g_2(x) \leq 0 \\ & \vdots \\ & g_r(x) \leq 0 \end{array}$$

Only  $\leq$  inequality constraints!

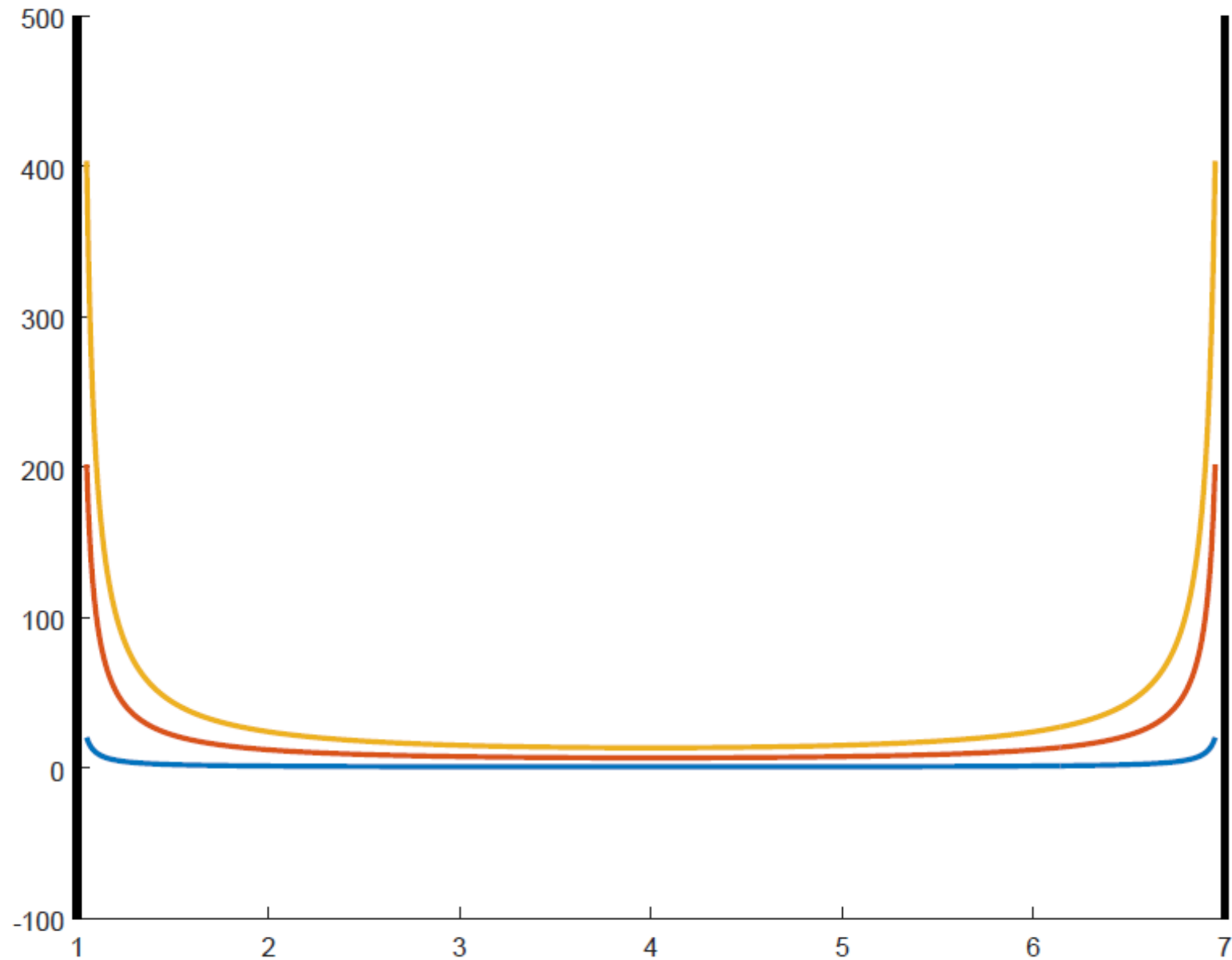
# Barrier

Barrier as we approach 0

$$f(x) - \sum_{j=1}^r \frac{1}{\phi_j} \cdot \frac{1}{g_j(x)}$$

where  $\phi_1, \phi_2, \dots, \phi_r > 0$  are fixed coefficients that determine how much weight is placed on violating a particular constraint.

# Barrier



# Barrier

We solve this!

$$\min_{x \in \mathbb{R}^n} \mathcal{F}_\phi(x) = f(x) - \sum_{j=1}^r \frac{1}{\phi_j} \cdot \frac{1}{g_j(x)}$$



# Barrier

In practice, we begin with small values for the  $\phi$ 's (setting them equal to one is a reasonable starting point) and begin using an iterative algorithm for UPs.

As we conduct iterations, we test to see if the constraint violations are getting smaller or not.

# Barrier

The  $\phi$ 's associated with constraints that are having their violations reduced are kept the same. The  $\phi$ 's associated with constraints that are not seeing an improvement in their violations are increased.

This is continued iteratively until all of the constraints are satisfied and the algorithm finds a stationary point of  $\mathcal{F}(x)$ , or another termination criteria (such as a limit on the number of iterations) is met.

# Barrier

1. Set  $k = 0$  and initialize  $x^k$  and  $\phi^k$ .
2. Solve:  $\min_{x \in \mathbb{R}^n} \mathcal{F}_{\phi^k}(x)$ , and get  $x^{k+1}$ .
3. If
$$|x^{k+1} - x^k| \leq \epsilon_1 \text{ and}$$
$$g(x^{k+1}) \leq \epsilon_2, \text{ stop.}$$
4. Otherwise update  $\phi$  as appropriate and continue in 2.

Barrier: Solve:  $\min_{x \in \mathbb{R}^n} \mathcal{F}_{\phi^k}(x)$ , and get  $x^{k+1}$ .

```
1: procedure GENERIC ITERATIVE ALGORITHM
2:    $k \leftarrow 0$  ▷ Set iteration counter to 0
3:   Fix  $x^0$  ▷ Fix a starting point
4:   while Termination criteria are not met do
5:     Find direction,  $d^k$ , to move in
6:     Determine step size,  $\alpha^k$ 
7:      $x^{k+1} \leftarrow x^k + \alpha^k d^k$  ▷ Update point
8:      $k \leftarrow k + 1$  ▷ Update iteration counter
9:   end while
10: end procedure
```

# Barrier: Example

# Barrier: Example

Consider the problem:

$$\begin{aligned} \min_x & f(x) \\ \text{s.t.} & a - x \leq 0 \\ & x - b \leq 0. \end{aligned}$$

# Barrier: Example

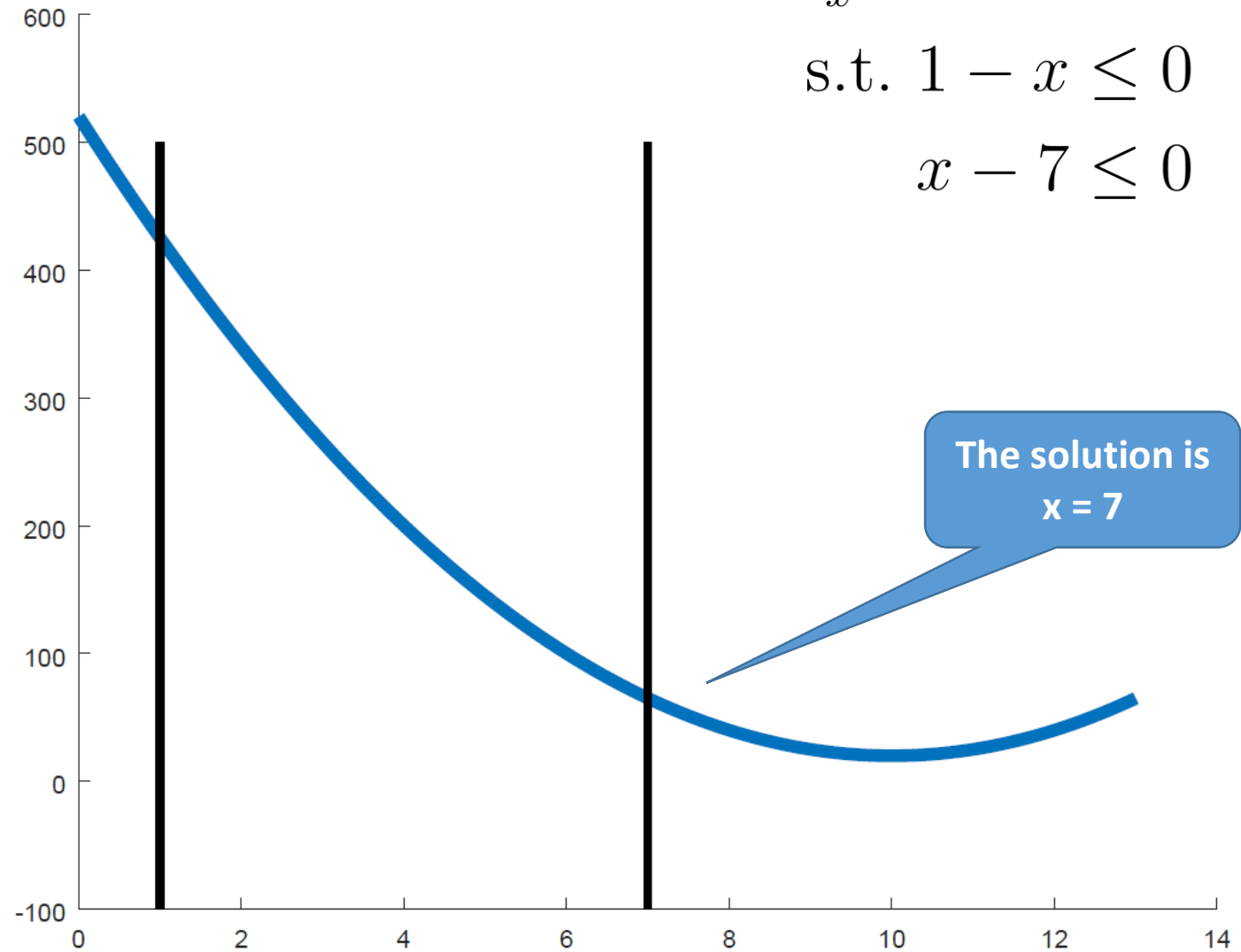
$$\begin{aligned} \min_x \quad & 5(x - 10)^2 - 20 \\ \text{s.t.} \quad & 1 - x \leq 0 \\ & x - 7 \leq 0 \end{aligned}$$

# Barrier: Example

$$\min_x 5(x - 10)^2 - 20$$

$$\text{s.t. } 1 - x \leq 0$$

$$x - 7 \leq 0$$

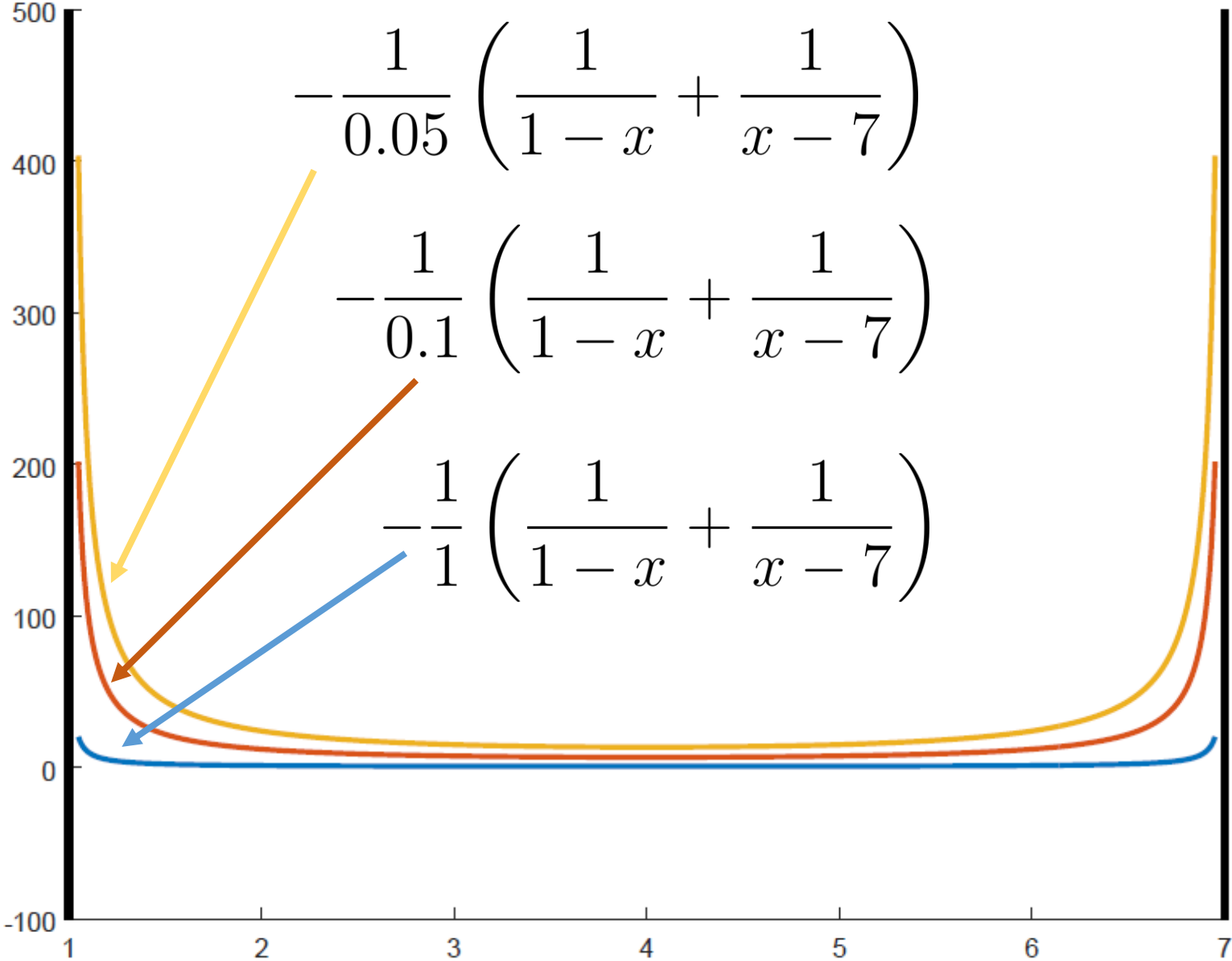




# Barrier: Example

```
clear
x = 0:1/100:13;
y = 5*(x-10).^2+20;
hold
plot(x,y,'LineWidth',5)
line([1 1],[-100 500],'LineWidth',3);
line([7 7],[-100 500],'LineWidth',3);
```

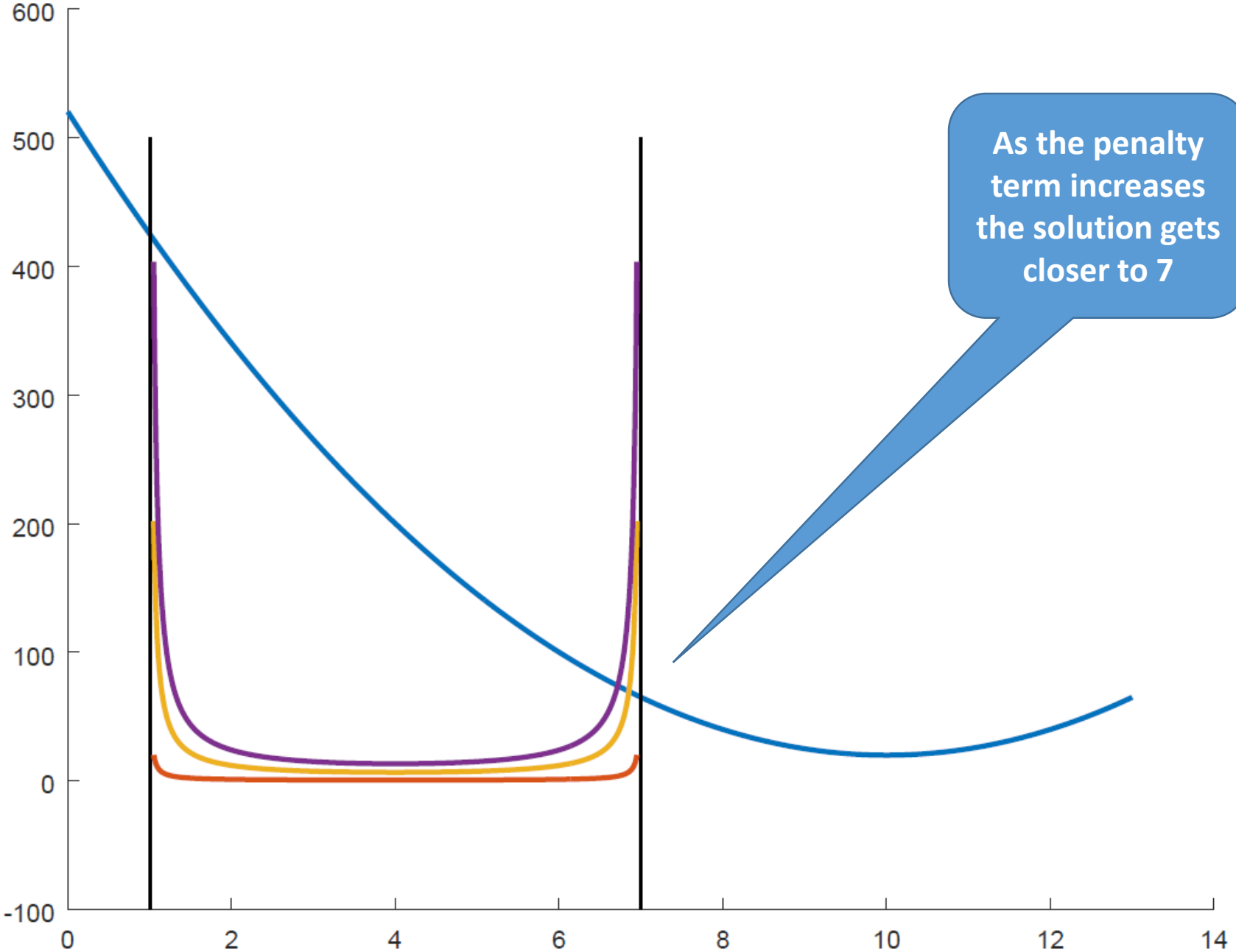
# Barrier: Example



# Barrier: Example

```
line([1 1],[-100 500],'LineWidth',3);  
line([7 7],[-100 500],'LineWidth',3);  
hold on  
x= 1.05:1/100:6.95;  
y1=-(1/1)*((1./(1-x))+(1./(x-7)));  
plot(x,y1,'LineWidth',2)  
y2=-(1/0.1)*((1./(1-x))+(1./(x-7)));  
plot(x,y2,'LineWidth',2)  
y3=-(1/0.05)*((1./(1-x))+(1./(x-7)));  
plot(x,y3,'LineWidth',2)
```

# Barrier: Example



# Barrier: Example

```
clear
x = 0:1/100:13;
y = 5*(x-10).^2+20;
hold
plot(x,y,'LineWidth',2)
line([1 1],[-100 500],'LineWidth',1);
line([7 7],[-100 500],'LineWidth',1);
hold on
x= 1.05:1/100:6.95;
y1=-(1/1)*((1./(1-x))+(1./(x-7)));
plot(x,y1,'LineWidth',2)
y2=-(1/0.1)*((1./(1-x))+(1./(x-7)));
plot(x,y2,'LineWidth',2)
y3=-(1/0.05)*((1./(1-x))+(1./(x-7)));
plot(x,y3,'LineWidth',2)
```

# GAMS

# GAMS

$$\min_x 5(x - 10)^2 - 20$$

$$\text{s.t. } 1 - x \leq 0$$

$$x - 7 \leq 0$$

```
variable x, z;  
equations fo, wall1, wall2;  
fo.. z =e= 5*power((x-10),2)-20;  
wall1.. 1-x =l= 0;  
wall2.. x-7 =l= 0;  
model barrier /all/;  
solve barrier using nlp minimizing z;  
option decimals = 8;  
display x.l, z.l;
```

# GAMS

$$\min_x 5(x - 10)^2 - 20$$

$$\text{s.t. } 1 - x \leq 0$$

$$x - 7 \leq 0$$

-----

9 VARIABLE x.L  
VARIABLE z.L

= 7.00000000

= 25.00000000



# A Different Barrier

$$\begin{aligned} \min_x \quad & 5(x - 10)^2 - 20 \\ \text{s.t.} \quad & 1 - x \leq 0 \\ & x - 7 \leq 0 \end{aligned}$$

$$\min_{x \in \mathbb{R}^n} \mathcal{F}_\phi(x) = f(x) - \sum_{j=1}^r \frac{1}{\phi_j} \cdot \log(-g_j(x))$$



A different barrier!

# A Different Barrier

$$\begin{aligned} \min_x \quad & 5(x - 10)^2 - 20 \\ \text{s.t.} \quad & 1 - x \leq 0 \\ & x - 7 \leq 0 \end{aligned}$$

$$\min_x \left[ 5(x - 10)^2 - 20 \right] - \left[ \frac{1}{\phi} \log(-(1 - x)) + \frac{1}{\phi} \log(-(x - 7)) \right]$$

# GAMS

$$\min_x [5(x - 10)^2 - 20] - \left[ \frac{1}{\phi} \log(-(1 - x)) + \frac{1}{\phi} \log(-(x - 7)) \right]$$

```
scalar phi /10000000/;  
variables x, z;  
x.l=4;  
equation fo;  
fo.. z =e= 5*power((x-10),2)+20 - (1/phi)*( log(-(1-x))+log(-(x-7)) );  
model barrier /all/;  
solve barrier using nlp minimizing z;  
option decimals = 8;  
display phi, x.l, z.l;
```

# GAMS

$$\min_x [5(x - 10)^2 - 20] - \left[ \frac{1}{\phi} \log(-(1 - x)) + \frac{1}{\phi} \log(-(x - 7)) \right]$$

```
----- 9 PARAMETER phi = 1.00000000
          VARIABLE x.L = 6.96720828
          VARIABLE z.L = 67.62042813

----- 9 PARAMETER phi = 10.00000000
          VARIABLE x.L = 6.99667221
          VARIABLE z.L = 65.49131329

----- 9 PARAMETER phi = 1.000000E+2
          VARIABLE x.L = 6.99966672
          VARIABLE z.L = 65.07214719

----- 9 PARAMETER phi = 1.000000E+3
          VARIABLE x.L = 6.99996667
          VARIABLE z.L = 65.00951720

----- 9 PARAMETER phi = 1.000000E+4
          VARIABLE x.L = 6.99999667
          VARIABLE z.L = 65.00118198
```

# GAMS

$$\min_x [5(x - 10)^2 - 20] - \left[ \frac{1}{\phi} \log(-(1 - x)) + \frac{1}{\phi} \log(-(x - 7)) \right]$$

```
----- 9 PARAMETER phi = 1.000000E+5
          VARIABLE x.L = 6.99999967
          VARIABLE z.L = 65.00014122

----- 9 PARAMETER phi = 1.000000E+6
          VARIABLE x.L = 6.99999997
          VARIABLE z.L = 65.00001642

----- 9 PARAMETER phi = 1.000000E+7
          VARIABLE x.L = 7.00000000
          VARIABLE z.L = 65.00000187
```

Different than  
25!

This is it!